

AMENDMENTS TO THE SPECIFICATION

Replace the first full paragraph on page 12 with the following:

A lengthwise-direction actuator 130 and a lateral-direction actuator 140 are provided in the body 10. The actuator 130 moves the frame 32 in the lengthwise direction, and the actuator 140 moves the frame 36 in the lateral direction. The actuator 130 includes a stepping motor 132 and a shaft 134 which converts a rotational movement of the stepping motor 132 to a liner movement and transmits the liner movement to the frame 32. A step number and a rotational direction of the stepping motor 132 are controlled by pulse signals output from the controller 120. The pulse signals contain information for moving the frame 32 in the direction opposite to the direction of the hand tremble and by an amount which equals the angular displacement, with respect to the lengthwise direction. Also, the lateral-direction actuator 140 has a structure similar to that of the lengthwise-direction actuator 130, including a stepping motor 142 and a shaft 144. Accordingly, the correction lenses 14L and 14R are moved in the two dimensional directions on the plane perpendicular to the optical axes OPL and OPR, so that the hand tremble is canceled.

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Replace the paragraph bridging pages 13 and 14 with the following:

The frame 32 is positioned such that the direction of the thickness is coincident with the optical axes OPR and OPL. The frame 32 is supported by first and second bars 42 and 52 at both ends 32a and 32b thereof in such a manner that the frame 32 is between the two bars 42 and 52. A bottom portion 44 of the first bar 42 is fixed on the inner wall 10a parallel to the optical axes OPR and OPL, by a screw 46, such that the longitudinal axis of the bar 42 is coincident with the lengthwise direction indicated by the arrow Y. Similarly, a bottom portion 54 of the second bar 52 is fixed on the inner wall 10a by a screw 56, such that the longitudinal axis of the bar 52 extends in the lengthwise direction. A side surface 42a of the first bar 42 and a side surface 52a of the second bar 52, facing each other, are parallel. The distance between the side surfaces 42a and 52a substantially equals the length of the frame 32 in the lateral direction. The frame 32 is put between the side surfaces 42a and 52a with a slight clearance, so that the frame 32 is prevented from moving in the lateral direction.

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Replace the paragraph bridging pages 34 and 35 with the following:

Figure 11 shows a third embodiment according to the present invention. It is a sectional view of another example of the pressing member. A pressing member 450 is a plunger. A ball 454 is provided at the end of the pressing member 450. A coil spring 458 is provided for urging the ball 454 in the direction in which the ball 454 is projected to the outside of the pressing member 450. Other structures are similar to those of the pressing member 350 of the second embodiment, including male threads 452 and female threads 474d.

Replace the first full paragraph on page 35 with the following:

The urging force, which is added to the shaft 134 by the pressing member 450, is predetermined in accordance with the projecting amount of the ball 454. The projecting amount of the ball 454 can be confirmed by sight. On the other hand, in the second embodiment, the urging force of the pressing member 350 should be confirmed using the torque screwdriver in the slit 356. However, in the third embodiment, it is unnecessary to use the special screwdriver in the slit 456, and a normal screwdriver can be used for the purpose of adjusting the engagement of the pressing member 450 and the tip end 474b of the guide pin 474.